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The main topic of Chapter 11 is the design of control systems using state variable models. Full-state feedback design and observer design methods based on pole placement are discussed. Tests for controllability and observability are presented, and the concept of an internal model design is discussed.

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Since $R(s) = 1/s$, we have $Y(s) = 6(s + 50) / s(s + 30)(s + 10)$

The partial fraction expansion of $Y(s)$ is given by $A_1/s + A_2/(s + 30) + A_3/(s + 10)$

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