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Measurement and Instrumentation: Theory and Application, Second Edition, introduces undergraduate engineering students to measurement principles and the range of sensors and instruments used for measuring physical variables. This updated edition provides new coverage of the latest developments in measurement technologies, including smart sensors, intelligent instruments, microsensors, digital recorders, displays, and interfaces, also featuring chapters on data acquisition and signal processing with LabVIEW from Dr. Reza Langari. Written clearly and comprehensively, this text provides students and recently graduated engineers with the knowledge and tools to design and build measurement systems for virtually any engineering application. Provides early coverage of measurement system design to facilitate a better framework for understanding the importance of studying measurement and instrumentation Covers the latest developments in measurement technologies, including smart sensors, intelligent instruments, microsensors, digital recorders, displays, and interfaces Includes significant material on data acquisition and signal processing with LabVIEW Extensive coverage of measurement uncertainty aids students' ability to determine the accuracy of instruments and measurement systems

An intuitive approach to machine learning covering key concepts, real-world applications, and practical Python coding exercises.

Providing a unique approach to machine learning, this text contains fresh and intuitive, yet rigorous, descriptions of all fundamental concepts necessary to conduct research, build products, tinker, and play. By prioritizing geometric intuition, algorithmic thinking, and practical real world applications in disciplines including computer vision, natural language processing, economics, neuroscience, recommender systems, physics, and biology, this text provides readers with both a lucid understanding of foundational material as well as the practical tools needed to solve real-world problems. With in-depth Python and MATLAB/OCTAVE-based computational exercises and a complete treatment of cutting edge numerical optimization techniques, this is an essential resource for students and an ideal reference for researchers and practitioners working in machine learning, computer science, electrical engineering, signal processing, and numerical optimization.

This text presents the subject of instrumentation and its use within measurement systems as an integrated and coherent subject. This edition has been thoroughly revised and expanded with new material and five new chapters. Features of this edition are: an integrated treatment of systematic and random errors, statistical data analysis and calibration procedures; inclusion of important recent developments, such as the use of fibre optics and instrumentation networks; an overview of measuring instruments and transducers; and a number of worked examples.

This textbook is appropriate for senior undergraduate and first year graduate students in mechanical and automotive engineering. The contents in this book are presented at a theoretical-practical level. It explains vehicle dynamics concepts in detail, concentrating on their practical use. Related theorems and formal proofs are provided, as are real-life applications. Students, researchers and practicing engineers alike will appreciate the user-friendly presentation of a wealth of topics, most notably steering, handling, ride, and related components. This book also: Illustrates all key concepts with examples Includes exercises for each chapter Covers front, rear, and four wheel steering systems, as well as the advantages and disadvantages of different steering schemes Includes an emphasis on design throughout the text, which provides a practical, hands-on approach

Measurement and Instrumentation introduces undergraduate engineering students to the measurement principles and the range of sensors and instruments that are used for measuring physical variables. Based on Morris's Measurement and Instrumentation Principles, this brand new text has been fully updated with coverage of the latest developments in such measurement technologies as smart sensors, intelligent instruments, microsensors, digital recorders and displays and interfaces. Clearly and comprehensively written, this textbook provides students with the knowledge and tools, including examples in LABVIEW, to design and build measurement systems for virtually any engineering application. The text features chapters on data acquisition and signal processing with LabVIEW from Dr. Reza Langari, Professor of Mechanical Engineering at Texas A&M University. Early coverage of measurement system design provides students with a better framework for understanding the importance of studying measurement and instrumentation Includes significant material on data acquisition, coverage of sampling theory and linkage to acquisition/processing software, providing students with a more modern approach to the subject matter, in line with actual data acquisition and instrumentation techniques now used in industry. Extensive coverage of uncertainty (inaccuracy) aids students' ability to determine the precision of instruments Integrated use of LabVIEW examples and problems enhances students' ability to understand and retain content

The second edition of this book would not have been possible without the comments and suggestions from students, especially those at Columbia University. Many of the new topics introduced here are a direct result of student feedback that helped refine and clarify the material. The intention of this book was to develop material that the author would have liked to have had available as a student. Theory of Applied Robotics: Kinematics, Dynamics, and Control (2nd Edition) explains robotics concepts in detail, concentrating on their practical use. Related theorems and formal proofs are provided, as are real-life applications. The second edition includes updated and expanded exercise sets and problems. New coverage includes: components and mechanisms of a robotic system with actuators, sensors and controllers, along with updated and expanded material on kinematics. New coverage is also provided in sensing and control including position sensors, speed sensors and acceleration sensors. Students, researchers, and practicing engineers alike will appreciate this user-friendly presentation of a wealth of robotics topics, most notably orientation, velocity, and forward kinematics.

We welcome you to the Third Pacific-Rim Symposium on Image and Video Technology (PSIVT 2009), sponsored by the National Institute of Informatics, Microsoft Research, and the Forum for Image Informatics in Japan. PSIVT 2009 was held in Tokyo, Japan, during January 13–16. The main conference comprised eight major themes spanning the field of image and video technology, namely, image sensors and multimedia hardware, graphics and visualization, image and video analysis, recognition and retrieval, multi-view imaging and processing, computer vision applications, video communications and networking, and multimedia processing. To heighten interest and participation, PSIVT also included workshops, tutorials, demonstrations and invited talks, in addition to the traditional technical presentations. For the technical program of PSIVT 2009, a total of 247 paper submissions underwent a full review process. Each of these submissions was evaluated in a double-blind manner by a minimum of three reviewers. The review assignments were determined by a set of two to four Chairs for each of the eight themes. Final decisions were jointly made by the Theme Chairs, with some adjustments by the Program Chairs in an effort to balance the quality of papers among the themes and to emphasize novelty. Rejected papers with significant discrepancies in

review evaluations received consolidation reports explaining the decisions.

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